

# Bayesian modelling of variance components makes analysis of resolvable incomplete block designs more efficient

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# Introduction

- Due to the development of statistical and computational methods, there is an increasing interest in adopting Bayesian approaches to METs data analysis,
- One of the advantages of the Bayesian approach is the possibility to define a prior probability distribution for parameters of interest,
- This allows taking into account the knowledge about parameters available before a new experiment,



# Introduction

- A prior distribution can be based on information available for the cultivars, its pedigree and trial locations
- The use of such additional information in cultivars evaluation and METs analysis is very rare



# Introduction

In order to increase the precision of the analysis of individual trials laid out as alpha designs in MET, we make a proposal to create a prior distribution of variance components for replicates, blocks and plots, based on the results of previous (historical) trials. We propose different modelling approaches for the prior distributions. Additionally, we evaluate the effectiveness of the Bayesian approach to the REML method classically used with MET.



# Material and Methods

## Historical data set

- come from real field trials with wheat of the Polish Post-Registration Variety Testing System
- grain yield from trials carried out between the 2009/2010 and 2019/2020 growing seasons
- each trials are carried out as alpha designs with two replicates, with the number of blocks depending on the number of cultivars



# Material and Methods

## Model

For individual trials laid out as alpha-designs we assume the linear model

$$y_{ijl} = \mu + \tau_i + \gamma_j + \rho_{l(j)} + \varepsilon_{ijl}$$

where,  $y_{ijl}$  is the yield response of the  $i$ th cultivar in the  $j$ th replicate and  $l$ th block within the  $j$ th replicate,  $\mu$  is the overall mean,  $\tau_i$  is the fixed effect of the  $i$ th cultivar,  $\gamma_j$  is the random effect of the  $j$ th replication,  $\rho_{l(j)}$  is the random effect of the  $l$ th block nested in the  $j$ th replication, and  $\varepsilon_{ijl}$  is the error effect.



# Material and Methods

For each individual trial the sequential sums of squares (Type I SS in SAS) were obtained for replicates,  $SS_r$ , blocks,  $SS_b$ , and error,  $SS_e$ , as well as their expected mean squares, which are functions of the three variance components for replicates  $\sigma_r^2$ , blocks  $\sigma_b^2$  and error  $\sigma_e^2$  (Table 1).

**Table 1: ANOVA table for random effects considered in study linear model.**

| Source     | Degrees of freedom (d.f.) | Sum of squares (SS) | Mean square (MS)  | Expected mean squares E(MS)                  |
|------------|---------------------------|---------------------|-------------------|--|
| Replicates | $v_r$                     | $SS_r$              | $MS_r = SS_r/v_r$ | $\sigma_e^2 + c_1\sigma_b^2 + c_2\sigma_r^2$ |
| Blocks     | $v_b$                     | $SS_b$              | $MS_b = SS_b/v_b$ | $\sigma_e^2 + c_3\sigma_b^2$                 |
| Error      | $v_e$                     | $SS_e$              | $MS_e = SS_e/v_e$ | $\sigma_e^2$                                 |



# Material and Methods

Conditionally on the variance components  $\theta = (\sigma_r^2, \sigma_b^2, \sigma_e^2)^T$ , the sums of squares have scaled central chi-squared distributions, i.e.

$$\frac{SS_i | \theta}{E(MS_i)} \sim \chi_{v_i}^2 \quad (i = r, b, e)$$

For the variance component vector  $\theta$ , we assume four different prior distribution specifications.





# Material and Methods

## Prior distribution

The first is a trivariate log-normal distribution, given by

$$\begin{pmatrix} \log(\sigma_r^2) \\ \log(\sigma_b^2) \\ \log(\sigma_e^2) \end{pmatrix} \sim MVN \left[ \begin{pmatrix} \theta_r \\ \theta_b \\ \theta_e \end{pmatrix}, \begin{pmatrix} \phi_r^2 & \phi_{rb} & \phi_{re} \\ & \phi_b^2 & \phi_{be} \\ & & \phi_e^2 \end{pmatrix} \right]$$

For this prior distribution we have two sets of hyperparameters,

- 1) the vector  $\theta$  of log-variance component means
- 2) the variance-covariance matrix  $\phi$  of the log-variance components



$$\theta = \begin{bmatrix} \theta_r \\ \theta_b \\ \theta_e \end{bmatrix} \quad \phi = \begin{bmatrix} \phi_r^2 & \phi_{rb} & \phi_{re} \\ & \phi_b^2 & \phi_{be} \\ & & \phi_e^2 \end{bmatrix}$$

# Material and Methods

The second prior, to ensure that the parameters of the variance-covariance matrix for the log-variances are properly constrained to suitable values, we used the following parameterizations of trivariate log-normal distribution:

$$\phi_r^2 = \exp(\lambda_{rr})$$

$$\phi_b^2 = \exp(\lambda_{bb})$$

$$\phi_e^2 = \exp(\lambda_{ee})$$

$$\pi_{rb} = \frac{\exp(2\lambda_{rb}) - 1}{\exp(2\lambda_{rb}) + 1}, \quad \phi_{rb} = \pi_{rb} \phi_r \phi_b$$

$$\pi_{re} = \frac{\exp(2\lambda_{re}) - 1}{\exp(2\lambda_{re}) + 1}, \quad \phi_{re} = \pi_{re} \phi_r \phi_e$$

$$\pi_{be} = \frac{\exp(2\lambda_{be}) - 1}{\exp(2\lambda_{be}) + 1}, \quad \phi_{be} = \pi_{be} \phi_b \phi_e$$

The exponential specification for the variances makes sure these are positive, whereas the use of the inverse of Fisher's z transformation ensures that a correlation  $\pi$  obeys the constraint  $|\pi| < 1$ .



# Material and Methods

## Prior distribution

Considered other prior distributions for the variances, we use the gamma and inverse gamma distributions. For these prior distributions, the shape parameter  $\alpha$ , the scale parameter  $\beta$  and variance-covariance matrix of the log-variance components  $\phi$  constitute hyper-parameters.



# Material and Methods

## Computational methods for Bayesian approach:

- empirical Bayes approach - PROC NLMIXED in SAS, used maximum likelihood estimation by adaptive Gauss-Hermite quadrature
- full Bayes approach – PROC MCMC in SAS, used the Markov Chain Monte Carlo (MCMC) method with Gibbs sampling



# Material and Methods

## Prior distribution

When we want implementing gamma and inverse gamma in the NLMIXED procedure of SAS, we faced the challenge that these only allow normally distributed random effects.

To fit these two typ of prior distribution, we use the inverse cumulative distribution function (c.d.f.) method.



# Material and Methods

## Simulations study

- Based on the historical data set we simulated new individual trials ( $n = 1000$ ).
- We use two schemes of simulations new trials
  - with a small number of blocks (2 blocks) and small size of blocks (3 plot per block)
  - with a relatively large number (10 blocks) and size of blocks (10 plot per block).



# Material and Methods

## Simulations study

Evaluation of prior distribution and computational methods

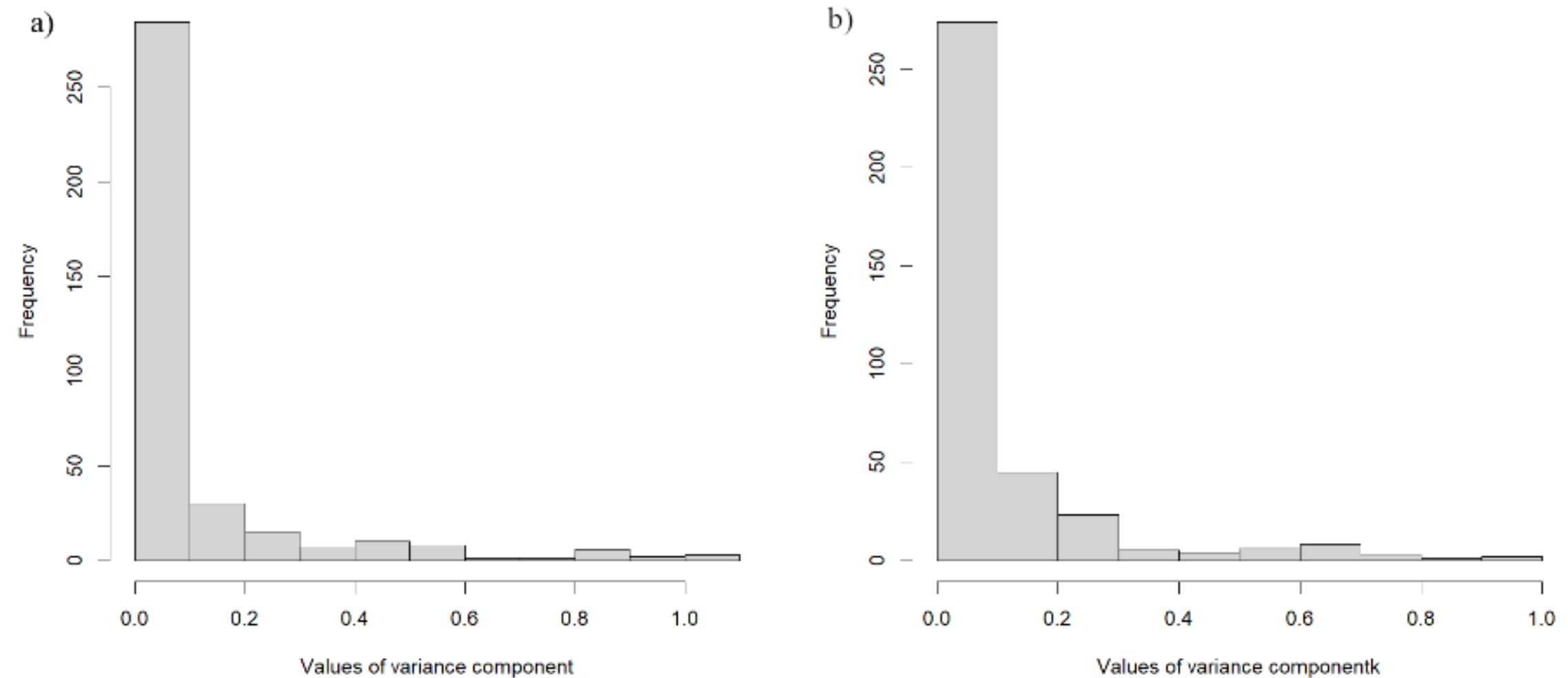
- the mean squared error of estimated treatment differences (MSED)
- the mean squared error (MSE)



# Results

## Historical data set – results of REML analysis

Figure 1. Values of variance components for replicate effects (a) and block effects (b) across individual trials from historical data set estimated by REML model.





# Results

## Symulation study - MSED

Table 2. The mean squared error of estimated treatment differences (MSED) for study models in two simulated data sets.

| Model                |                      | 3 plots per block | 10 plots per block |
|----------------------|----------------------|-------------------|--------------------|
|                      |                      |                   |                    |
| <b>REML</b>          |                      | 2.6126            | 2.0755             |
| <b>NLMIXED</b>       | 3-variate normal (1) | 1.9195            | 1.9965             |
|                      | 3-variate normal (2) | 1.9181            | 1.9443             |
|                      | Gamma                | 1.9099            | 1.9221             |
|                      | Invers gamma         | 1.8919            | 1.9081             |
| <b>Full Bayesian</b> | 3-variate normal (1) | 1.8543            | 1.9906             |
|                      | 3-variate normal (2) | 1.8291            | 1.8996             |
|                      | Gamma                | 1.8011            | 1.9034             |
|                      | Invers gamma         | 1.8102            | 1.8855             |



# Results

## Symulation study - MSE

Table 3. The mean squared error (MSE) of variance components for study models in two simulated data sets.

| Model                       |                      | Variance components for replication |                    | Variance components for block |                    | Variance components for error |                    |
|-----------------------------|----------------------|-------------------------------------|--------------------|-------------------------------|--------------------|-------------------------------|--------------------|
|                             |                      | 3 plots per block                   | 10 plots per block | 3 plots per block             | 10 plots per block | 3 plots per block             | 10 plots per block |
|                             |                      | <b>REML</b>                         |                    | 0.4726                        | 0.2545             | 0.3953                        | 0.1229             |
| <b>NLMIXED</b>              | 3-variate normal (1) | 0.3696                              | 0.2298             | 0.3133                        | 0.1109             | 0.0321                        | 0.0123             |
|                             | 3-variate normal (2) | 0.3687                              | 0.2292             | 0.3128                        | 0.1099             | 0.0321                        | 0.0121             |
|                             | Gamma                | 0.3483                              | 0.2291             | 0.3051                        | 0.1091             | 0.0320                        | 0.0119             |
|                             | Invers gamma         | 0.3466                              | 0.2284             | 0.3048                        | 0.1084             | 0.0320                        | 0.0121             |
| <b>Full Bayesian (MCMC)</b> | 3-variate normal (1) | 0.3511                              | 0.2265             | 0.3088                        | 0.1017             | 0.0317                        | 0.0109             |
|                             | 3-variate normal (2) | 0.3502                              | 0.2261             | 0.3081                        | 0.1012             | 0.0323                        | 0.0111             |
|                             | Gamma                | 0.3398                              | 0.226              | 0.3029                        | 0.1019             | 0.0321                        | 0.0109             |
|                             | Invers gamma         | 0.3387                              | 0.2244             | 0.3022                        | 0.1006             | 0.0318                        | 0.0103             |



# Conclusions

- **The Bayesian approach with prior distribution built on historical data set demonstrated non-negligible gains in precision and recovery inter-block information in compare to REML methods**
- **This benefit of the Bayesian approach is more strongly observed for simulated data in the 3 plots per block scheme**
- **The difference between the two computational methods was small, but in favour of full Bayes approach**





**Thank you for your attention**



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